

To complete [Task], a service robot generates [Initial Plan]. However, the robot finds [Situation] at that specific step that prevents it from completing the task. The robot tries to generate [New Plan] to complete the task by using [Objects] in the environment. Please determine whether the task can be completed by a robot.

A successful task plan is defined as one that fulfills a user's service request through actions that the robot is capable of executing and are acceptable to humans. In addition, common factors that could render a plan unsuccessful include, but are not limited to, the inclusion of non-existent objects in the environment, actions that the robot is unable to execute, or missing essential steps between actions.

For each question, you need to answer either "Yes" or "No" indicating if you believe the action plan completes the task.

**Task:**

Provide water for humans to drink

**Actions that can be executed by robots:**

walk, run, grab, switch on, switch off, open, close, find, put, fill, clean, wash

**Initial Plan:**

Step 1: The robot walks from dining room to kitchen room.

Step 2: The robot finds faucet in kitchen room.

Step 3: The robot finds cup in kitchen room.

Step 4: The robot grasps cup in kitchen room.

Step 5: The robot switches on faucet in kitchen room.

Step 6: The robot fills cup with water in kitchen room.

Step 7: The robot walks from kitchen room to dining room.

Step 8: The robot puts cup on the table in dining room.

Step 9: The robot walks from dining room to kitchen room.

Step 10: The robot switches off faucet in kitchen room.

**Situation:**

When the robot is going to hold the cup, it finds that the cup is broken.

**Objects:**

['table cloth', 'piano bench', 'couch', 'closet', 'dish', 'mug', 'faucet', 'cutlery fork', 'cleaning bottle', 'wine glass', 'dish bowl', 'bookshelf', 'dining', 'wooden chopstick', 'rag', 'cutting board', 'mat', 'condiment bottle', 'oven tray', 'table', 'coffee cup', 'colander', 'drinking glass', 'desk', 'bucket', 'cloth napkin', 'kitchen cabinet', 'kitchen table', 'nightstand', 'coffee filter', 'condiment shaker', 'coffee table', 'cutlery knife', 'dish rack', 'frying pan', 'chef knife', 'paper towel', 'pantry', 'dining table', 'kitchen counter', 'measuring cup', 'cooking pot', 'cpu table', 'cupboard', 'sponge', 'wooden chair', 'wooden spoon', 'kitchen', 'cup', 'trash can']

**New Plan:**

Step 1: The robot walks from dining room to kitchen room.

Step 2: The robot finds faucet in kitchen room.

Step 3: The robot finds drinking glass in kitchen room.

Step 4: The robot grasps drinking glass in kitchen room.

Step 5: The robot switches on faucet in kitchen room.

Step 6: The robot fills drinking glass with water in kitchen room.

Step 7: The robot walks from kitchen room to dining room.

Step 8: The robot puts drinking glass on the table in dining room.

Step 9: The robot walks from dining room to kitchen room.

Step 10: The robot switches off faucet in kitchen room.